

CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims

1. (original) A system comprising:
a first highline;
a second highline;
a first skate coupled to said first highline;
a second skate coupled to said second highline;
a three sheave supporter coupled to said first skate and said second skate;
a platform coupled to said three sheave supporter;
an XZ movement rope configured to move said platform; and,
a Y movement rope pair configured to move said platform.
2. (original) The system of claim 1 further comprising a plurality of sheaves through which said XZ movement rope and said Y movement rope pair travel.
3. (original) The system of claim 1 further comprising:
an X movement motor coupled with said XZ movement rope;
at least one Y movement motor coupled with said Y movement rope pair; and,
a Z movement motor coupled with an end of said XZ movement rope.
4. (original) The system of claim 3 further comprising an electrical generator coupled to said X movement motor and said at least one Y movement motor and said Z movement motor.
5. (original) The system of claim 1 further comprising at least one dynamometer for measuring the tension of said XZ movement rope and said Y movement rope pair.

6. (original) The system of claim 1 further comprising a stabilizer mounted on said platform.
7. (original) The system of claim 1 wherein said platform is coupled with a camera.
8. (original) The system of claim 1 wherein said platform is coupled with a mechanical claw.
9. (original) The system of claim 1 wherein said platform is coupled with a loader.
10. (original) The system of claim 1 wherein said platform is coupled with a mining scoop.
11. (original) The system of claim 1 wherein said platform further comprises a downward pointing camera for remotely viewing from the position of said platform.
12. (original) The system of claim 1 wherein said platform is attached to a flight simulating suit.
13. (original) The system of claim 1 further comprising support structures.
14. (original) A method comprising:
coupling a first skate to a first highline;
coupling a second skate to a second highline;
coupling a three sheave supporter to said first skate and said second skate;
coupling a platform to said three sheave supporter;
configuring an XZ movement rope to move said platform; and,
configuring a Y movement rope pair to move said platform.
15. (original) The method according to claim 14 further comprising:
coupling said XZ movement rope to an X movement motor;

coupling said Y movement rope pair to at least one Y movement motor; and,
coupling said XZ movement rope to a Z movement motor.

16. (original) The method according to claim 15 further comprising:
rotating said X movement motor;
rotating said at least one Y movement motor;
rotating said Z movement motor; and,
moving said platform.

17. (original) A system comprising:
means for coupling a first skate to a first highline;
means for coupling a second skate to a second highline;
means for coupling a three sheave supporter to said first skate and said second skate;
means for coupling a platform to said three sheave supporter;
means for configuring an XZ movement rope to move said platform; and,
means for configuring a Y movement rope pair to move said platform.

18. (original) The system of claim 17 further comprising:
means for coupling said XZ movement rope to an X movement motor;
means for coupling said Y movement rope to at least one Y movement motor; and,
means for coupling said XZ movement rope to a Z movement motor.

19. (original) The system of claim 18 further comprising:
means for rotating said X movement motor;
means for rotating said at least one Y movement motor;
means for rotating said Z movement motor; and,
means for moving said platform.

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20. (original) The system of claim 19 further comprising:
means for stabilizing said platform.